

Eidgenössische Technische Hochschule Zürich Swiss Federal Institute of Technology Zurich

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I. Introduction

Motivation

Shape-from-Blur [1] and Motion-from-Blur [2] tackle the **rigid body** tracking and reconstruction from blurry images. How to address the same problem for the **soft body**? Best application case: Human body motion blur.

Challenge

- Dataset almost unavailable
- Many factors determine blur amount



5 ms







25 ms 50 ms

Exposure time, Motion speed

Blur Formation

 $\sum \mathcal{R}_{S}(\Theta_{i}) \Big) \cdot B + \frac{1}{N} \sum \mathcal{R}_{S}(\Theta_{i}) \cdot \mathcal{R}_{F}(\Theta_{i})$ $\hat{I} = \left(1 - \frac{1}{N}\sum \mathcal{I}\right)$ Inverse alpha channel Background Blurred foreground (human)

 $\mathcal{R}_{S}(\Theta_{i})$ Differentiable rendered soft-silhouette $\mathcal{R}_F(\Theta_i)$ Differentiable rendered foreground object $\Theta_i = SMPL(\theta_{t=i}, \beta) + T_{t=i}$ Mesh driven by SMPL [3]





Assumption: Each blur frame contains a short temporal motion of period N



Human Pose Tracking from Blurry Images Denys Rozumnyi¹ Jie Song¹ Otmar Hilliges¹ Marc Pollefeys^{1,3} Martin R. Oswald^{1,2} ETH Zürich¹, Universiteit van Amsterdam², Microsoft³

III. Pipeline Real Scenario Cropped Input Frames Input Frames 100 ms Human Pose Estimation Clean Background IV. Experiments Single Frame -----. Input Initialization •----- ${\mathcal T}$ Txture



METRO [5] DOM ~ 0 [4] Ontimized $1 \sum \mathcal{D}$							Multiframes			
METRO [5]			BGMv2 [4]		Optimized $\frac{1}{n} \sum \mathcal{R}_S$		Frame #1			
	Ŕ									
	- MA					GT				
						Ours				
	N N]+[2]				
						BIN[1				
	K	K	Ŕ	Ŕ	N		Subframes of #1			
	- MA	- MA	- The second sec	- File			V. Conclusion			
	Image: Second				t=N	(Θ_i)	 → Key idea: Approaching the problem from a generative describing a fully differentiable forward problemry images from a given 3D human mod Denys Rozumnyi, Martin R. Oswald, Vittorio Ferrari, and Marc Pollefeys. Shape notion of fast moving objects. In NeurIPS 2021. Denys Rozumnyi, Martin R. Oswald, Vittorio Ferrari, and Marc Pollefeys. Motio motion-blurred objects in videos. In CVPR 2022. Loper, Matthew and Mahmood, Naureen and Romero, Javier and Pons-Moll, G Person Linear Model. In SIGGRAPH Asia 2015. Shanchuan Lin, Andrey Ryabtsev, Soumyadip Sengupta, Brian Curless, Steve Sei resolution background matting. In CVPR 2021. Kevin Lin, Lijuan Wang, and Zicheng Liu. End-to-end human pose and mesh recei [6] Naureen Mahmood, Nima Ghorbani, Nikolaus F. Troje, Gerard Pons-Moll, and Pas surface shapes. In ICCV 2019. Q Ma et al. Learning to Dress 3D People in Generative Clothing. In CVPR 2020. 			



. Conclusion

→ Key idea:

Approaching the problem from a generative viewpo describing a fully differentiable forward process to blurry images from a given 3D human model.

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'e propose the first method to reconstruct sub-frame human motion and textured shape from substantially blurred images. \rightarrow Core of method'

\rightarrow	Core or	method.				
point and generate	der reconstruction losses(Image formation loss and Matting loss) w to solve the inverse problem with standard gradient descent S.					
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